# Exploring the Earth's Magnetic Field Using Satellites – From Ørsted to Swarm

Nils Olsen

DTU Space Technical University of Denmark

#### Bullard Lecture 2016







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# Exploring Earth's Interior Using Satellite Magnetic Field Observations – From Ørsted to Swarm

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Thanks to the Ørsted, CHAMP and Swarm teams

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## Sir Edward Bullard

#### PROFILE Sir Edward Bullard



Chairman of Britain's space projects

New Scientist, 21 June 1959

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## Sir Edward Bullard



Chairman of Britain's space projects

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"Interests centres on the variations in the magnetic field at different heights, at different times of day and in different states of the Sun. Satellite measurements ... may give the data from which the variable effects can be eliminated – by comparison with simultaneous measurements on the ground.

It should then be possible to confirm or deny the present belief that the Earth's magnetic field is in some way distorted."

> Nigel Calder: Some exciting possibilities New Scientist, 21 May 1959

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- Satellites for Measuring Earth's Magnetic Field
- 2 Swarm Satellite Trio
- The Recent Geomagnetic Field and Core Field Dynamics
- The Lithospheric Field
- **5** Conclusions and Outlook

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#### Outline of Talk

- Satellites for Measuring Earth's Magnetic Field
  - 2 Swarm Satellite Trio
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- 5 Conclusions and Outlook



Credit: C. Barton

Satellites for Measuring Earth's Magnetic Field **POGO** 1965-70

Satellites for Measuring Earth's Magnetic Field



Satellites for Measuring Earth's Magnetic Field







## Satellites for Exploring Earth's Magnetic Field



- POGO satellites (OGO-2, OGO-4, OGO-6) only scalar field *F*
- Magsat (1979 1980) first satellite to measure vector B

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#### Continuous measurements since 1999

- Ørsted (1999 2014)
- SAC-C (2000 2005)
- CHAMP (2000 2010)
- ... and now Swarm satellite trio

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with ground observatories ...

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with ground observatories ... ... and 1 day of satellite data

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with ground observatories ... ... and 4 days of satellite data (single satellite)

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with ground observatories ... ... and 1 day of Swarm data (three satellites)

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• Ground stations monitor time changes of Earth's magnetic field at fixed locations  Satellites move (with 8 km/s): mixture of temporal and spatial changes

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- Ground stations monitor time changes of Earth's magnetic field at fixed locations
- Use of time averaged values (hourly, monthly, annual means) to reduce rapid external field contributions
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- Time-averaging of observations is *not* possible: one has to work with (possibly down-sampled) instantaneous values

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- Absolute measurements of **B** from Geomagnetic observatories

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• Absolute measurements of **B** from High-precision Satellites

- Ground stations monitor time changes of Earth's magnetic field at fixed locations
- Use of time averaged values (hourly, monthly, annual means) to reduce rapid external field contributions
- Absolute measurements of **B** from Geomagnetic observatories
- External field studies using data from variometer stations; no (stable) baseline for **B**

- Satellites move (with 8 km/s): mixture of temporal and spatial changes
- Time-averaging of observations is *not* possible: one has to work with (possibly down-sampled) instantaneous values
- Absolute measurements of **B** from High-precision Satellites
- External field studies (mainly in polar regions and for active conditions) using satellites without absolute measurements

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### Sources of the Near-Earth Magnetic Field

#### Sources of the Near-Earth Magnetic Field

Crust

Mantle

Fluid outer core

Magnetized rocks

(non magnetic)

Movement of molten iron

## Sources of the Near-Earth Magnetic Field

- Internal sources
  - fluid outer core: 94%

electrical currents created by motion of a conducting fluid

- lithosphere: 3% magnetized rocks
- External sources
  - current systems in ionosphere and magnetosphere: 3%, but highly time-variable! caused by solar particles, fields, and radiation





## $B_r$ at 400 km altitude



## $B_r$ at 400 km altitude

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## The Swarm Satellite Constellation Mission

Constellation of 3 satellites to explore Earth's magnetic field and its environment

- launched on 22 Nov 2013 10+ years lifetime
- two satellites (Swarm Alpha and Charlie) side-by-side (< 150 km separation at equator) at 450 km altitude (Dec 2016), measuring East-West magnetic gradient
- third satellite (Swarm Bravo) at 530 km altitude (Dec 2016)
- See http://earth.esa.int/swarm

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High-precision measurements of **B** (< 1 nT) and of  $F = |\mathbf{B}|$  (< 0.3 nT)

Level-1b data product: Time series of  ${\bf B}$  at 1 Hz (MAG-LR) and at 50 Hz (MAG-HR)

All Swarm data products are freely available at http://earth.esa.int/swarm

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#### Precise positions (< few cm)

All Swarm data products are freely available at  $\ensuremath{\mathsf{http://earth.esa.int/swarm}}$ 

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Accelerometer data (only for Swarm Charlie, reduced quality)

All Swarm data products are freely available at  $\ensuremath{\mathsf{http://earth.esa.int/swarm}}$ 

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Electric Field, plasma density, ion and electron temperatures

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#### Evolution of the Swarm constellation

- Each spacecraft samples all Local Times within 9 months
- Present LT difference between Alpha/Charlie and Bravo is 4.5 hrs
- decaying altitude

re-entry of lower pair Alpha/Charlie in mid 2020 or even later?





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Swarm Satellite Trio

# Swarm Alpha, 2 May 2014, Quiet day (Kp $\leq$ 0+)



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CHAOS-6 model removed for core ...

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#### Swarm Alpha, 2 May 2014, Quiet day (Kp $\leq$ 0+)



CHAOS-6 model removed for core + magnetosphere ...

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CHAOS-6 model removed for core + magnetosphere + lithosphere

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Credit: C. Barton

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#### Magnetic Field Model

Assumption: no local electric currents ( $\nabla \times \mathbf{B} = 0$ ): **B** is a potential field

$$\mathbf{B} = -\nabla V$$

$$V = a \sum_{n=1}^{N} \sum_{m=0}^{n} \left[ g_n^m \cos m\phi + h_n^m \sin m\phi \right] \left( \frac{a}{r} \right)^{n+1} P_n^m \left( \cos \theta \right)$$

$$+ a \sum_{n=1}^{N} \sum_{m=0}^{n} \left[ q_n^m \cos m\phi + s_n^m \sin m\phi \right] \left( \frac{r}{a} \right)^n P_n^m \left( \cos \theta \right)$$

 $r, \theta, \phi$  are spherical coordinates

 $g_n^m, h_n^m$  and  $q_n^m, s_n^m$  describe internal, resp. external, magnetic field contributions Time dependence of low-degree ( $n \le 20$ ) coefficients  $g_n^m(t), h_n^m(t)$  described by splines

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#### CHAOS-6: Model Determined from 17 Years of Satellite Data

Goal: To describe magnetic field with high temporal resolution (determine rapid core field changes) and high spatial resolution (lithospheric field)

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- Data selection for magnetic field data (**B**, *F*):
  - geomagnetic activity index  $\mathit{Kp} \leq$  20,  $|\mathit{dD_{st}}/\mathit{dt}| \leq$  2nT/hr
  - $\bullet\,$  only data from dark regions, Sun at least  $10^\circ\,$  below horizon
  - Polar regions (>  $\pm 55^{\circ}$  magnetic latitude): only F, selected based on Interplanetary Magnetic Field

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  - Polar regions (>  $\pm 55^{\circ}$  magnetic latitude): only F, selected based on Interplanetary Magnetic Field
- Data selection for magnetic "gradient" data  $(\Delta \mathbf{B}, \Delta F)$ :
  - N-S gradient approximated by alongtrack first differences (15 s sampling) E-W gradient approximated by difference *Swarm Alpha - Swarm Charlie*
  - allow for higher activity:  $\textit{Kp} \leq$  30,  $|\textit{dD}_{st}/\textit{dt}| \leq$  3nT/hr
  - only scalar data in polar regions

(Finlay et al., 2016; Olsen et al., 2014)

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#### Model Determined from 17 Years of Satellite Data

- Model parameterization:
  - static field (core and lithosphere) up to  $n \leq 120$
  - time variation of core field  $(n \le 20)$  described by splines with 6 month knot spacing between 1997.1 and 2016.6
  - co-estimation of external field and instrument calibration

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  - co-estimation of external field and instrument calibration
- Iteratively Reweighted Least Squares to account for non-Gaussian data errors
- Regularisation of mean temporal complexity of  $|d^3B_r/dt^3|^2$  at CMB  $10 \times$  more heavy regularisation of zonal coefficients  $g_n^0$  ... and regularisation of temporal complexity of  $\ddot{B}_r$  at model endpoints
- Regularisation of  $||B_r||^2$  at surface for n > 75

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Alternative models include GRIMM (Lesur et al., 2008, 2010), POMMME (Maus et al., 2005, 2006), Comprehensive Model (CM) (Sabaka et al., 2002, 2004, 2015), ...

#### CHAMP Scalar Residuals

Aug 2000 to Sept 2010

mean  $\pm 1\sigma$  in 2° bins

non-polar latitudes: 1.95 nT rms

 $\approx 5\times$  larger residuals at polar latitudes due to unmodeled external contributions



### Swarm East-West Scalar Difference Residuals

mean  $\pm 1\sigma$  in 2° bins

non-polar latitudes: 0.38 nT rms

 $\approx 3\times$  larger residuals at polar latitudes

Difference of instantaneous measurements between the two satellites *Swarm Alpha* and *Swarm Charlie* 

Note different data selection criteria for  $>\pm55^\circ\text{magnetic}$  latitudes



#### Residual scatter vs. latitude: Field Data



- Enhanced scatter in auroral region
- $B_r$  is least disturbed (in non-polar regions)
- Smallest scatter in F at  $\pm 35^{\circ}$ where magnetospheric ring-current field is  $\perp$  to internal dipole field

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#### Residual scatter vs. latitude: Gradient Data

scalar gradients, day and night



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#### Residual scatter vs. latitude: Gradient Data

scalar and vector gradients, only nightside



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### Core Field Dynamics during the last 15 years $B_r$ at CMB in 2015, n = 1 - 13



(Finlay et al., 2016)

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# Core Field Dynamics during the last 15 years $\dot{B}_r$ at CMB in 2015, n = 1 - 16



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(Finlay et al., 2016)

#### Core Field Dynamics during the last 15 years $\ddot{B}_r$ at CMB in 2015. n = 1 - 16



Consistent picture of

- spatial structure of (time-averaged) secular variation
- secular acceleration
  - at large length scales (n < 9)

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(Finlay et al., 2016)

#### An accelerating high-latitude Jet in Earth's Core

Livermore, Finlay, Hollerbach (2016)

CHAOS-6 SV in 2015



CHAOS-6 MF in 2015



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Flow Model



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SV from Flow Model



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5) Conclusions and Outlook





Credit: C. Barton

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#### The Geomagnetic Spectrum

$$R_n = \langle \mathbf{B}_n \cdot \mathbf{B}_n \rangle$$
  
=  $(n+1) \sum_{m=0}^n \left[ (g_n^m)^2 + (h_n^m)^2 \right]$ 

mean square magnetic field at Earth's surface (r = a) due to contributions with horizontal wavelength  $\lambda_n = \frac{2\pi a}{n}$ 

(Lowes, 1966; Mauersberger, 1956)



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#### Lithospheric signature at various altitudes



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#### Lithospheric signature at various altitudes



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#### Lithospheric signature at various altitudes



Lithospheric signal for  $n = 100 \ (\lambda = 400 \ \text{km})$ :

54 pT @ 300 km altitude 25 pT @ 350 km altitude 5.6 pT @ 450 km altitude

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 20 months of Swarm data, selection as for CHAOS-6: scalar and vector field data (F, B)
 N-S scalar and vector gradient data: alongtrack first differences
 E-W scalar and vector gradient data: Alpha – Charlie

(Olsen et al., 2015, 2016)

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- 20 months of Swarm data, selection as for CHAOS-6: scalar and vector field data (F, B)
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- Core field up to spherical harmonic degree n = 13, crustal field up to n = 80Co-estimation of external fields and instrument alignment parameters

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- Core field up to spherical harmonic degree n = 13, crustal field up to n = 80Co-estimation of external fields and instrument alignment parameters
- Three different models:
  - Only field data (F, B)
  - Field and scalar gradient data ( $F, \mathbf{B}, \Delta F$  )
  - Field and scalar + vector gradient data (F, B,  $\Delta F, \Delta B$ )

(Olsen et al., 2015, 2016)

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  - Field and scalar + vector gradient data (F, B,  $\Delta F, \Delta B$ )
- ... and compare with the CHAMP-derived model MF7 (Maus, 2010)

(Olsen et al., 2015, 2016)

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 $\mathsf{SIFM}_{\mathrm{no}\ \mathrm{gradients}}$ : no gradient data



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SIFM<sub>no gradients</sub>: no gradient data SIFM: scalar gradients



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MF7, (Maus, 2010) SIFM<sub>no gradients</sub>: no gradient data SIFM: scalar gradients SIFM+: ... vector gradients added



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MF7, (Maus, 2010) SIFM<sub>no gradients</sub>: no gradient data SIFM: scalar gradients SIFM+: ... vector gradients added CHAOS-6: Model from 2 years of CHAMP data at 320 km altitude (10 x higher crustal field signal at n = 100)

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- What part of the model is defined (constrained) by the observations?
- Small-scale structure of *all* global lithospheric field models are regularized
  - CHAOS-6 (Finlay et al., 2016) and MF7 (Maus, 2010): only part n ≤ 75 is purely determined by observations, part n = 76 133 is constrained by "additional information"

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- What kind of regularization ("additional information") should one use ?
- Often used: minimization of  $||B_r||_2^2$  at surface  $(L_2$ -norm) ... but also Maximum Entropy minimization or  $L_1$ -norm  $||B_r||_1$  is used

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Important ingredients for successful field modelling:

• Account for non-lithospheric contributions as much as possible by data selection and by model co-estimation

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- Data misfit: Account for non-Gaussian data errors (robust data processing)

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- Model regularization: which norm, which quantity to regularize?

- Same CHAMP data as for CHAOS-6 (but only 2009 2010 when altitude < 350 km) 15 sec sampling, geomagnetic quiet conditions scalar and vector fields (**B**, *F*); scalar and vector alongtrack gradients (Δ**B**, Δ*F*)
- Removal of CHAOS-6 core field ( $n \le 15$ ) and magnetospheric field
- No further data treatment (no orbit-by-orbit filtering, no "line-levelling")

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Nils Olsen (DTU Space)

- Same CHAMP data as for CHAOS-6 (but only 2009 2010 when altitude < 350 km) 15 sec sampling, geomagnetic quiet conditions scalar and vector fields (**B**, *F*); scalar and vector alongtrack gradients (Δ**B**, Δ*F*)
- Removal of CHAOS-6 core field ( $n \le 15$ ) and magnetospheric field
- No further data treatment (no orbit-by-orbit filtering, no "line-levelling")
- Model parametrized by 35,000 "point sources" (monopoles) located 100 km below surface
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- Final step: Representation by spherical harmonics up to n = 185 ensuring  $abla \cdot {f B} = 0$

The Lithospheric Field



MF7 Lithospheric Model





### $B_r$ at Earth's surface: Arctic



### $B_r$ at Earth's surface: Antarctic



# A latitudinal profile over the North-Pole n = 16 - 133





#### Good agreement at satellite altitude

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# A latitudinal profile over the North-Pole n = 16 - 133





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Good agreement at satellite altitude and at surface in non-polar regions

# A latitudinal profile over the North-Pole n = 100 - 133





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Good agreement at  $n \ge 100$  in non-polar regions, confirming robustness of lithospheric models up to (at least) n = 100, though not in polar regions

#### Outline of Talk

Satellites for Measuring Earth's Magnetic Field

2) Swarm Satellite Trio

3 The Recent Geomagnetic Field and Core Field Dynamics

4 The Lithospheric Field

**(5)** Conclusions and Outlook





#### Conclusions

- Thanks to the satellites Ørsted, CHAMP and now Swarm, there is a consistent picture of
  - secular variation up to spherical harmonic degree n = 16
  - lithospheric field (at least up to n = 100)
- Consideration of external (ionospheric and magnetospheric) magnetic field signatures is one of the biggest challenges for extracting core and lithospheric field signal
- Rapid core field variations and lithospheric field are better resolved in non-polar ( $<\pm60^\circ$ ) regions
- Magnetic gradients from the Swarm constellation help to reduce (but do not remove!) external field contamination

   improved lithosphere and core field models
- Bright future: Swarm will likely continue for 10+ years

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- Physics-based field modeling (e.g. through data assimilation)


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Conclusions and Outlook



MF7 Lithospheric Model





## Geomagnetic Spectra at Earth's surface



Nils Olsen (DTU Space)