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AUSPOS Online GPS Processing Report

Space Geodesy Analysis Centre
Geohazards Division, Geoscience Australia

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This document is a report of the GPS data processing undertaken by the AUSPOS Online GPS Processing Service. The AUSPOS Online GPS Processing Service uses International GPS Service (IGS) products (final, rapid, ultra-rapid depending on availability) including Precise Orbits, Earth Orientation, Coordinate Solutions (IGS-SSC) to compute precise coordinates in ITRF anywhere on Earth. The Service is designed to process only dual frequency GPS phase data.

The AUSPOS Online GPS Processing Service is a free service and you are encouraged to use it for your projects. However, you may not charge others for this service. Geoscience Australia does not warrant that this service a) is error free; b) meets the customer's requirements. Geoscience Australia shall not be liable to the customer in respect of any loss, damage or injury (including consequential loss, damage or injury) however caused, which may arise directly or indirectly in respect of this service.

An overview of the GPS processing strategy is attached to this report. Please direct email correspondence to geodesy@ga.gov.au

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1 User and IGS GPS Data

All antenna heights refer to the vertical distance from the Ground Mark to the Antenna Reference Point (ARP).

User File	Antenna Type	Antenna Height (m)	Start Time	End Time
SCOR1111.08o	DEFAULT (NONE)	0.0000	2008-04-20 00:00:00	2008-04-20 23:59:59

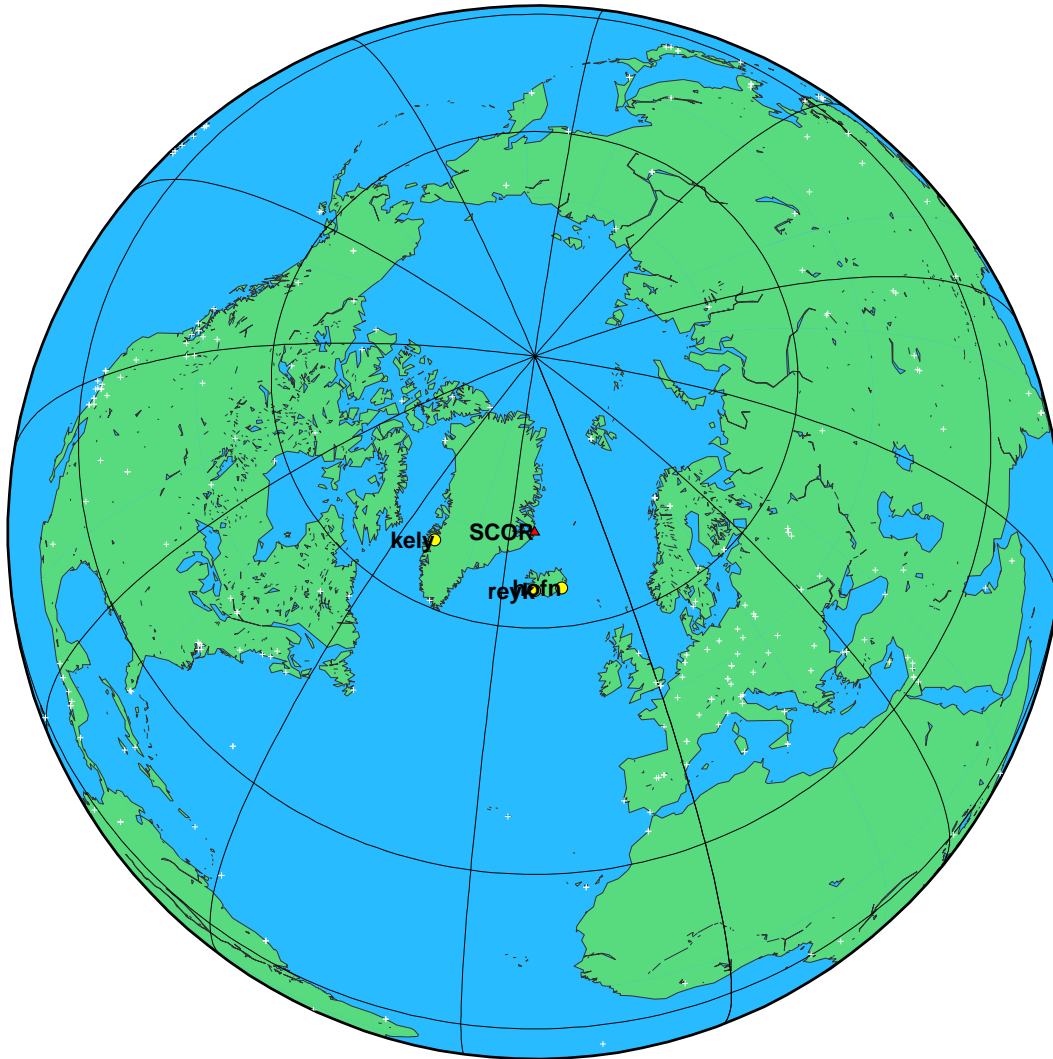


Figure 1: Global View – submitted GPS station(s) and nearby IGS GPS stations used in the processing; triangle(s) represent submitted user data; circle(s) represent the nearest available IGS stations.

2 Processing Summary

Date	IGS Data	User Data	Orbit Type
2008-04-20	reyk hofn kely	SCOR	IGS Final

3 Computed Coordinates, ITRF2000

All computed coordinates are based on the IGS realisation of the ITRF2000 reference frame, provided by the IGS cumulative solution. All the given ITRF2000 coordinates refer to a mean epoch of the site observation data. All coordinates refer to the Ground Mark.

3.1 Cartesian, ITRF2000

	X(m)	Y(m)	Z(m)	ITRF2000 @
kely	1575559.035	-1941827.948	5848076.502	2008/04/20
reyk	2587384.233	-1043033.534	5716564.047	2008/04/20
hofn	2679689.972	-727951.176	5722789.362	2008/04/20
SCOR	1982096.126	-798821.033	5989464.865	2008/04/20

3.2 Geodetic, GRS80 Ellipsoid, ITRF2000

The height above the Geoid is computed using the GPS Ellipsoidal height and subtracting a Geoid-Ellipsoid separation. Geoid-Ellipsoidal separations, in this section, are computed using a spherical harmonic synthesis of the global EGM96 geoid. More information on the EGM96 geoid can be found at earth-info.nga.mil/GandG/wgsegm/egm96.html

	Latitude(DMS)			Longitude(DMS)		Ellipsoidal Height(m)	Above-Geoid Height(m)
kely	66	59	14.7075	-50-56	-41.4227	229.817	198.320
reyk	64	8	19.6251	-21-57	-19.7517	93.014	26.592
hofn	64	16	2.2525	-15-11	-52.5109	82.746	18.027
SCOR	70	29	7.2027	-21-57	-1.2144	128.843	73.014

4 Solution Information

To validate your solution you should check the :-

- i. Antenna Reference Point (ARP) to Ground Mark records;
- ii. Apriori Coordinate Updates (valid range is 0.000 - 15.000 m);
- iii. Coordinate Precision (valid range is 0.001 - 0.025 m);
- iv. Root Mean Square (RMS) (valid range is 0.0005 - 0.0250 m); and
- v. % Observations Deleted (valid range is 0 - 25) %;

4.1 ARP to Ground Mark, per day

All heights refer to the vertical distance from the Ground Mark to the Antenna Reference Point (ARP). The Antenna Offsets refer to the vertical distance from the ARP to the L1 phase centre.

Station	Height(m)	Antenna Offsets(m)			yyyy/mm/dd
	Up	East	North	Up	
SCOR	0.0000	0.0000	0.0000	0.0000	2008/04/20

4.2 Apriori Coordinate Updates - Cartesian, per day

	dX(m)	dY(m)	dZ(m)	yyyy/mm/dd
SCOR	0.007	-0.002	0.006	2008/04/20

4.3 Coordinate Precision - Cartesian, per day

1 Sigma	sX(m)	sY(m)	sZ(m)	yyyy/mm/dd
SCOR	0.003	0.003	0.005	2008/04/20

4.4 RMS, Observations, Deletions per day

Data	RMS (m)	# Observations	% Obs. Deleted	Date
kely	0.0053	17208	14 %	2008-04-20
reyk	0.0058	19563	10 %	2008-04-20
SCOR	0.0054	56004	11 %	2008-04-20

A GPS Computation Standards

A.1 Measurement Modelling

Observable	Ionosphere corrected L1 double difference carrier phase, Psuedo-range only used for receiver clock estimation, Elevation cut-off 15°, Sampling rate 30 seconds, Weighting 1.0cm for double difference, elevation dependent $1/\sin(E)$.
Troposphere	Hopfield, Niell mapping function
Preprocessing	Receiver clocks estimated using pseudo-range information
Satellite center of mass correction	Block II x,y,z: 0.2794, 0.0000, 1.0259 m Block IIA x,y,z: 0.2794, 0.0000, 1.2053 m
Satellite Antenna Phase centre calibration	Not applied
Ground Antenna phase centre calibrations	Elevation-dependent phase centre corrections are applied according to the model IGS01, the NGS antenna calibrations are used when the antenna used is not a recognised IGS type. The corrections are given relative to the Dorne Margolin T antenna.
Atmospheric Drag	Jachhia Model
Centre of Mass Correction / Attitude	Nil

A.2 Orbit Modelling

Earth's Gravitational (Static) Potential Model	EGM96 - degree and order 12
Solid Earth Tides (Dynamic) Potential	Love Model
Ocean Tide (Dynamic) Potential	Christodoulidis
Third Body Perturbations	Sun, Moon and Planets Values for physical constants - AU, Moon/Earth mass ratio, GM(moon, sun and planets) from JPL DE403 Planetary Ephemeris.
Direct Solar Radiation Pressure	Rock

A.3 Station Position Modelling and Reference Frame

Precession	IAU76/IERS96
Nutation	IAU80/IERS96 (including epsilon and psi corrections)
Sine terms added to accumulated precession and nutation in Right Ascension	As in IERS TN 21, p. 21
Geodesic Nutation	As in IERS TN 21, P. 37
Polar Motion	IGS Earth Orientation Parameters (Ultra-rapid, Rapid, Final) - apriori
Earth Rotation (UT1)	IGS Earth Orientation Parameters (Ultra-rapid, Rapid, Final) - apriori
Daily and Sub-daily tidal corrections to X, Y and UT1	Applied (IERS2000)
Plate Motion	IGS Cumulative SSC
Planetary and Lunar Ephemeris	JPL DE403
Station Displacement - Solid Earth Tide Loading	Williamson and Diamante (1972) + Wahr (1980) for the frequency dependent elastic response of the Earth's fluid interior.
Station Displacement - Ocean Tide Loading	not applied
Station Displacement - Pole Tide	applied
Station Displacement - Atmosphere Loading	not applied
Reference Frame	IGS Cumulative SSC